

1. Initial Angular Velocity: $\omega_{a_i} := 200 \frac{\text{rad}}{\text{s}}$ $\omega_{b_i} := 200 \frac{\text{rad}}{\text{s}}$
2. Initial Inertia: $I_{a_i} := .5 \cdot \text{m}^2 \cdot \text{kg}$ $I_{a_e} := .4 \cdot \text{m}^2 \cdot \text{kg}$ $I_{b_i} := .5 \cdot \text{m}^2 \cdot \text{kg}$ $I_{b_e} := .6 \cdot \text{m}^2 \cdot \text{kg}$
3. Output Inertia (fixed): $I_c := 5 \cdot \text{m}^2 \cdot \text{kg}$
4. Initial Momentum: $L_{a_i} := I_{a_i} \cdot \omega_{a_i}$ $L_{a_i} = 100 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$ $L_{b_i} := I_{b_i} \cdot \omega_{b_i}$ $L_{b_i} = 100 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$
5. Set the desired ending angular velocity and calculate the output momentum (Lc).
Ending ang. vel. for output (manually entered at step 14) will be when the torque on FW A & FW B are equal:
- $\omega_c = 20.408 \frac{1}{\text{s}}$
- $L_c := I_c \cdot \omega_c$ $L_c = 102.041 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$
6. Find ending momentum that satisfies ending ω_c and ending Lc:

6.1. Start with the eq. for a differential:

$$\omega_c := \frac{\omega_{a_e} - \omega_{b_e}}{2}$$

6.2. Since ending angular velocities ($\omega_{a,b}$) aren't known, substitute the momentum/inertia eq.:

$$\omega_c := \frac{\frac{L_{a_e}}{I_{a_e}} - \frac{L_{b_e}}{I_{b_e}}}{2}$$

$$\omega_c = 20.408 \frac{1}{\text{s}}$$

6.3. Eliminate L_{a_e} by substituting the total initial momentum ($L_{a_i} + L_{b_i}$) minus $L_c - L_{b_e}$ so that the only unknown is L_{b_e} :

$$\omega_c := \frac{(L_{a_i} + L_{b_i}) - L_c - L_{b_e}}{2 \cdot I_{a_e}} - \frac{L_{b_e}}{2 \cdot I_{b_e}}$$

$$\omega_c = 20.408 \frac{1}{\text{s}}$$

6.4. Move terms so that you can solve for L_{b_e} :

$$L_{b_e} := \frac{I_{b_e} \cdot [(2 \cdot \omega_c \cdot I_{a_e}) - (L_{a_i} + L_{b_i}) + L_c]}{-I_{b_e} - I_{a_e}}$$

$$L_{b_e} = 48.979 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

6.5. Knowing L_{b_e} allows
computation of L_{a_e}

$$L_{a_e} := (L_{a_i} + L_{b_i}) - L_c - L_{b_e}$$

$$L_{a_e} = 48.979 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

6.6. Knowing L_{a_e} and L_{b_e}
allows computation of
both FW ending velocities:

$$\omega_{a_e} := \frac{L_{a_e}}{I_{a_e}}$$

$$\omega_{a_e} = 122.448 \frac{1}{\text{s}}$$

$$\omega_{b_e} := \frac{L_{b_e}}{I_{b_e}}$$

$$\omega_{b_e} = 81.632 \frac{1}{\text{s}}$$

6.7. All of the computed data:

$$\omega_{a_i} = 200 \frac{1}{\text{s}}$$

$$\omega_{a_e} = 122.448 \frac{1}{\text{s}}$$

$$L_{a_i} = 100 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

$$L_{a_e} = 48.979 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

$$\omega_{b_i} = 200 \frac{1}{\text{s}}$$

$$\omega_{b_e} = 81.632 \frac{1}{\text{s}}$$

$$L_{b_i} = 100 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

$$L_{b_e} = 48.979 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

$$\omega_{c_i} := 0$$

$$\omega_c = 20.408 \frac{1}{\text{s}}$$

$$L_c = 102.041 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

7. Conservation of Momentum:

$$L_i := L_{a_i} + L_{b_i}$$

$$L_i = 200 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

$$L_e := L_{a_e} + L_{b_e} + L_c$$

$$L_e = 200 \frac{\text{m}^2 \cdot \text{kg}}{\text{s}}$$

8. Kinetic Energy:

$$E_{kai} := \frac{1}{2} \cdot I_{a_i} \cdot \omega_{a_i}^2$$

$$E_{kai} = 1 \times 10^4 \text{ J}$$

$$E_{kae} := \frac{1}{2} \cdot I_{a_e} \cdot \omega_{a_e}^2$$

$$E_{kae} = 2.999 \times 10^3 \text{ J}$$

$$E_{kbi} := \frac{1}{2} \cdot I_{b_i} \cdot \omega_{b_i}^2$$

$$E_{kbi} = 1 \times 10^4 \text{ J}$$

$$E_{kbe} := \frac{1}{2} \cdot I_{b_e} \cdot \omega_{b_e}^2$$

$$E_{kbe} = 4.498 \times 10^3 \text{ J}$$

9. Delta Kinetic Energy:

$$E_{ka} := E_{kai} - E_{kae}$$

$$E_{ka} = 7.001 \times 10^3 \text{ J}$$

$$E_{kb} := E_{kbi} - E_{kbe}$$

$$E_{kb} = 5.502 \times 10^3 \text{ J}$$

$$E_{kc} := \frac{1}{2} \cdot I_c \cdot \omega_c^2$$

$$E_{kc} = 1.041 \times 10^3 \text{ J}$$

10. Time to Change Moments: $t_r := 10 \cdot s$ $t := 0 \cdot s, .0001 \cdot s .. t_r$

11. Inertia as a function of time: $I_a(t) := I_{a_i} + t \cdot \frac{I_{a_e} - I_{a_i}}{t_r}$ $I_b(t) := I_{b_i} + t \cdot \frac{I_{b_e} - I_{b_i}}{t_r}$

12. Momentum as a function of time: $L_a(t) := L_{a_i} + t \cdot \frac{L_{a_e} - L_{a_i}}{t_r}$ $L_b(t) := L_{b_i} + t \cdot \frac{L_{b_e} - L_{b_i}}{t_r}$

13. Velocity as a function of time: $\omega_a(t) := \frac{L_a(t)}{I_a(t)}$ $\omega_b(t) := \frac{L_b(t)}{I_b(t)}$

$$\omega_c(t) := \frac{\omega_a(t) - \omega_b(t)}{2} \quad L_c(t) := I_c \cdot \omega_c(t)$$

14. Find ω_c that satisfies equal torque on FW A & FW B: $\omega_c \equiv 20.4083 \cdot \frac{\text{rad}}{s}$

15. Calculate torque: $tqa(t) := \frac{d}{dt} L_a(t)$ $tqb(t) := \frac{d}{dt} L_b(t)$

$$tqa(.0001 \cdot s) = -45.157 \text{ in} \cdot \text{lbf} \quad tqb(.0001 \cdot s) = -45.157 \text{ in} \cdot \text{lbf}$$

$$tqa(t_r) = -45.157 \text{ in} \cdot \text{lbf} \quad tqb(t_r) = -45.157 \text{ in} \cdot \text{lbf}$$

$$tqa := \frac{L_{a_e} - L_{a_i}}{t_r} \quad tqa = -45.157 \text{ in} \cdot \text{lbf}$$

$$tqb := \frac{L_{b_e} - L_{b_i}}{t_r} \quad tqb = -45.157 \text{ in} \cdot \text{lbf}$$

$$tqc := \frac{L_c(t_r)}{t_r} \quad tqc = 90.314 \text{ in} \cdot \text{lbf}$$