



This diagram demonstrated the idea of a loop which can be moved in such a way as to keep both  $\Phi_F$  and  $\Phi_{*F}$  constant.

Loops B and C are close together, creating a disc. The disc is made up of two flat surfaces connected by a thin surface

which lies in the calumoid, made up from a collection of elementary bivectors  $\Sigma = \frac{\partial P}{\partial a} \wedge \frac{\partial P}{\partial b}$ . From the definition of the calumoid, it is clear that, as  $\Phi_F$  and  $\Phi_{*F}$  are equal on both faces of the disc, then  $\int \langle F, \Sigma \rangle da db$  and  $\int \langle *F, \Sigma \rangle da db$  must be zero.

This does not, however, mean that  $\langle F, \Sigma \rangle = 0$  and  $\langle *F, \Sigma \rangle = 0$ .

In my diagram above, I have drawn it so that  $\langle *F, \Sigma \rangle = 0$  as the loop slides up and down lines of force so everywhere  $*F$  is parallel to the surface of  $P$  - no bongs of the bell. The same cannot be said for  $\frac{F}{*F}$ . Indeed it is possible to reverse the situation so that  $\frac{F}{*F}$  is parallel to the surface, or even construct a calumoid where neither  $F$  nor  $*F$  is parallel to the surface of the elementary bivectors.

Moving on to part (c):

$$\langle F, \Sigma \rangle = 0$$

$$\langle *F, \Sigma \rangle = 0.$$

$$\therefore F_{\mu\nu} \left( \frac{\partial x^\mu}{\partial a} \frac{\partial x^\nu}{\partial b} - \frac{\partial x^\nu}{\partial a} \frac{\partial x^\mu}{\partial b} \right) da_\mu db_\nu = 0$$

and

$$*F_{\mu\nu} \left( \frac{\partial x^\mu}{\partial a} \frac{\partial x^\nu}{\partial b} - \frac{\partial x^\nu}{\partial a} \frac{\partial x^\mu}{\partial b} \right) da_\mu db_\nu = 0.$$

$$\Rightarrow \frac{\partial x^\mu}{\partial a} \frac{\partial x^\nu}{\partial b} - \frac{\partial x^\nu}{\partial a} \frac{\partial x^\mu}{\partial b} = 0.$$

$$\therefore \left. \begin{aligned} x^\mu &= x^\mu(\phi^\mu(a)) \\ x^\nu &= x^\nu(\phi^\nu(a)) \end{aligned} \right\} A$$

$$\text{or } \left. \begin{aligned} x^\mu &= x^\mu(\theta^\mu(b)) \\ x^\nu &= x^\nu(\theta^\nu(b)) \end{aligned} \right\} B$$

But because  $\mu, \nu$  occurs in all combinations of  $\mu(0 \dots 3), \nu(0 \dots 3)$

there can be no mixing of the solutions, it is either A or B.

But a solution which depends on  $(a)$  only is a line not a surface.

In part (a) there is a solution involving the two parameters  $a$  and  $b$

because  $F = -E_x dt \wedge dx$  leads to  $*F = -E_x dy \wedge dz$  so there

are two sets of mutually exclusive  $\mu$  and  $\nu$  in  $(0,1)$  and  $(2,3)$ .

Combining A and B produces the answer given.