



$$T = \frac{1}{2} m_1 \dot{a}^2 + \frac{1}{2} m_2 \dot{b}^2 + \frac{1}{2} m_1 (r+a)^2 \dot{\theta}_1^2 + \frac{1}{2} m_2 (r+b)^2 \dot{\theta}_2^2$$

$$U = \frac{1}{2} k a^2 + \frac{1}{2} k b^2 - m_1 g (r+a) \cos \theta_1 - m_2 g (r+b) \cos \theta_2$$

Holonomic constraint

$$(x, y)_{m_1} = ((r+a) \sin \theta_1 + l, (r+a) \cos \theta_1) = \bar{R}_1$$

$$(x, y)_{m_2} = ((r+b) \sin \theta_2, (r+b) \cos \theta_2) = \bar{R}_2$$

$$F_C = (\bar{R}_1 - \bar{R}_2) \cdot (\bar{R}_1 - \bar{R}_2) - l^2 = 0$$

Coordinate system: θ_1 & $\theta_2 \Rightarrow$ cylindrical

a & $b \Rightarrow$ radial

x & $y \Rightarrow$ Cartesian, only used for holonomic constraint.